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# Solving Differential Equations with MATLAB

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# Solving Differential Equations in MATLAB

MATLAB have lots of built-in functionality for solving differential equations. MATLAB includes functions that solve ordinary differential equations (ODE) of the form:

$$\frac{dy}{dt} = f(t, y), \quad y(t_0) = y_0$$

MATLAB can solve these equations numerically.

Higher order differential equations must be reformulated into a system of first order differential equations.

**Note!** Different notation is used:

$$\frac{dy}{dt} = y' = \dot{y}$$

Not all differential equations can be solved by the same technique, so MATLAB offers lots of different ODE solvers for solving differential equations, such as **ode45**, **ode23**, **ode113**, etc.

# Bacteria Population

In this task we will simulate a simple model of a bacteria population in a jar.

The model is as follows:

$$\text{birth rate} = bx$$

$$\text{death rate} = px^2$$

Then the total rate of change of bacteria population is:

$$\dot{x} = bx - px^2$$

Set  $b=1$ /hour and  $p=0.5$  bacteria-hour

→ Simulate the number of bacteria in the jar after **1 hour**, assuming that initially there are **100 bacteria** present.

```
function dx = bacteriadiiff(t,x)
% My Simple Differential Equation
```

```
b=1;
p=0.5;
```

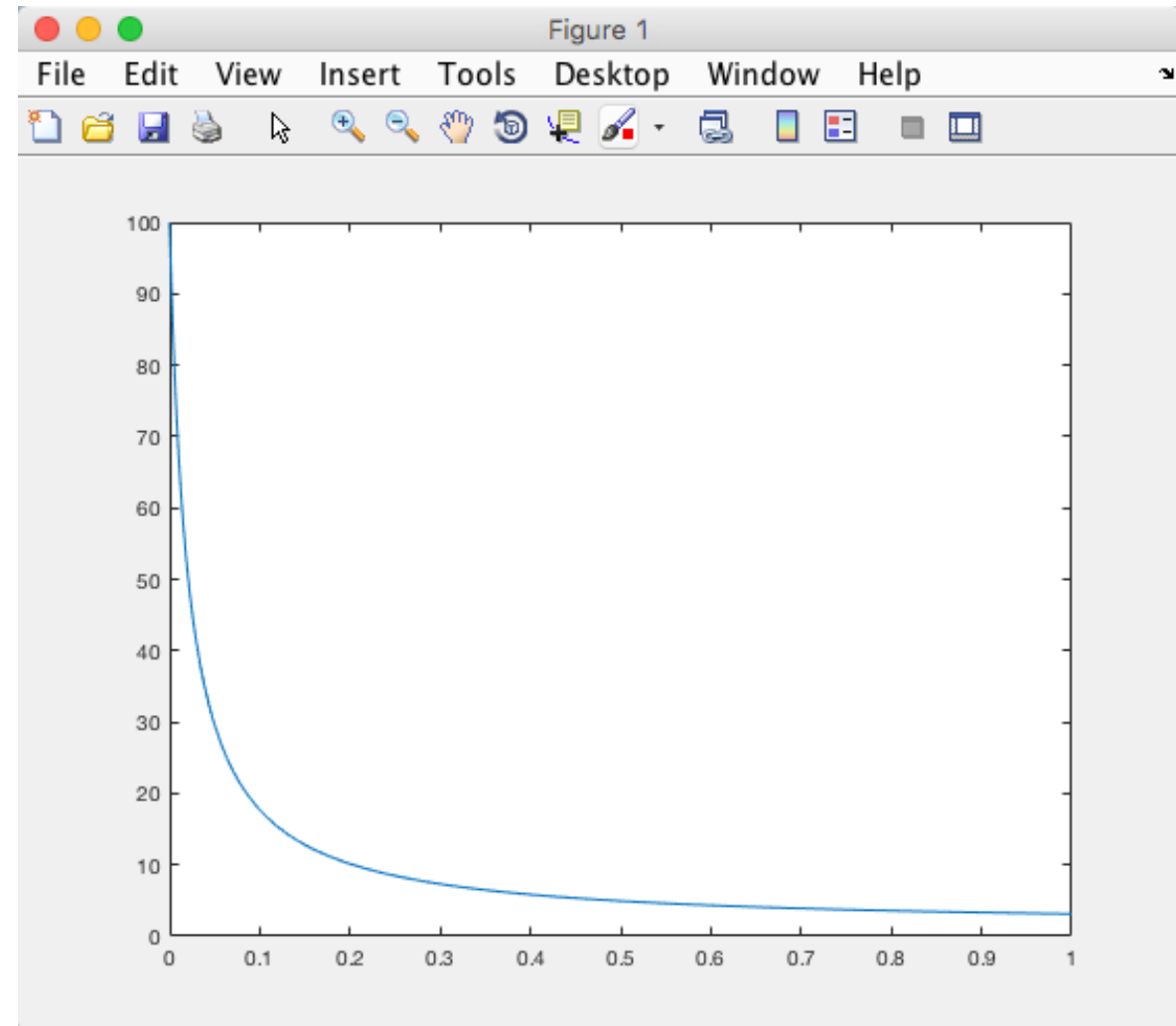
```
dx = b*x - p*x^2;
```

```
clear
clc
```

```
tspan=[0 1];
x0=100;
```

```
[t,y]=ode45(@bacteriadiiff, tspan,x0);
plot(t,y)
```

```
[t,y]
```



# Passing Parameters to the model

Given the following system (1.order differential equation):

$$\dot{x} = ax + b$$

where  $a = -\frac{1}{T}$ , where  $T$  is the time constant

In this case we want to pass  $a$  and  $b$  as parameters, to make it easy to be able to change values for these parameters

We set  $b = 1$

We set initial condition  $x(0) = 1$  and  $T = 5$ .

Solve the Equation and Plot the results with MATLAB

```
function dx = mysimplediff(t,x,param)
% My Simple Differential Equation
```

```
a=param(1);
b=param(2);
```

```
dx=a*x+b;
```

```
tspan=[0 25];
```

```
x0=1;
```

```
a=-1/5;
```

```
b=1;
```

```
param=[a b];
```

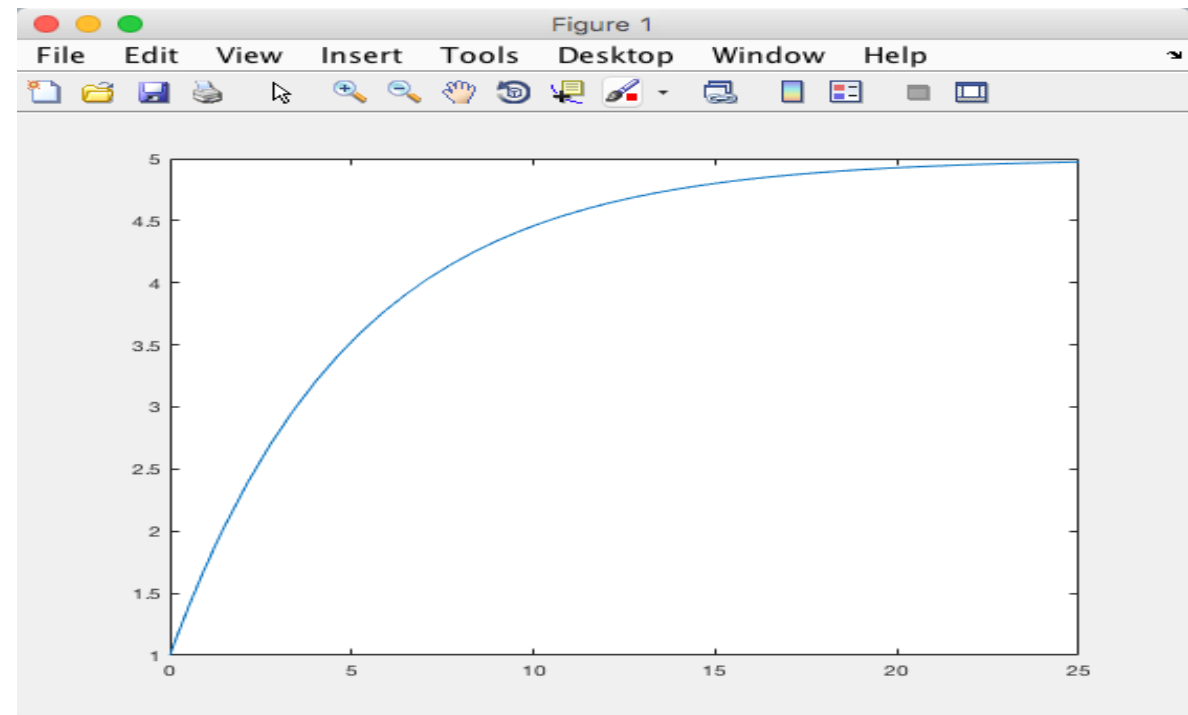
```
[t,y]=ode45(@mysimplediff, tspan,
```

```
x0,[], param);
```

```
plot(t,y)
```

By doing this, it is very easy to change values for the parameters  $a$  and  $b$ .

**Note!** We need to use the 5. argument in the ODE solver function for this. The 4. argument is for special options and is normally set to “[]”, i.e., no options.



# Differential Equation

Use the ode23 function to solve and plot the results of the following differential equation in the interval  $[t_0, t_f]$ :

$$w' + (1.2 + \sin 10t)w = 0$$

Where:

$$t_0 = 0$$

$$t_f = 5$$

$$w(t_0) = 1$$

# Differential Equation

We start by rewriting the differential equation:

$$w' = -(1.2 + \sin 10t)w$$

Then we can implement it in MATLAB



```
function dw = diff_task3(t,w)
```

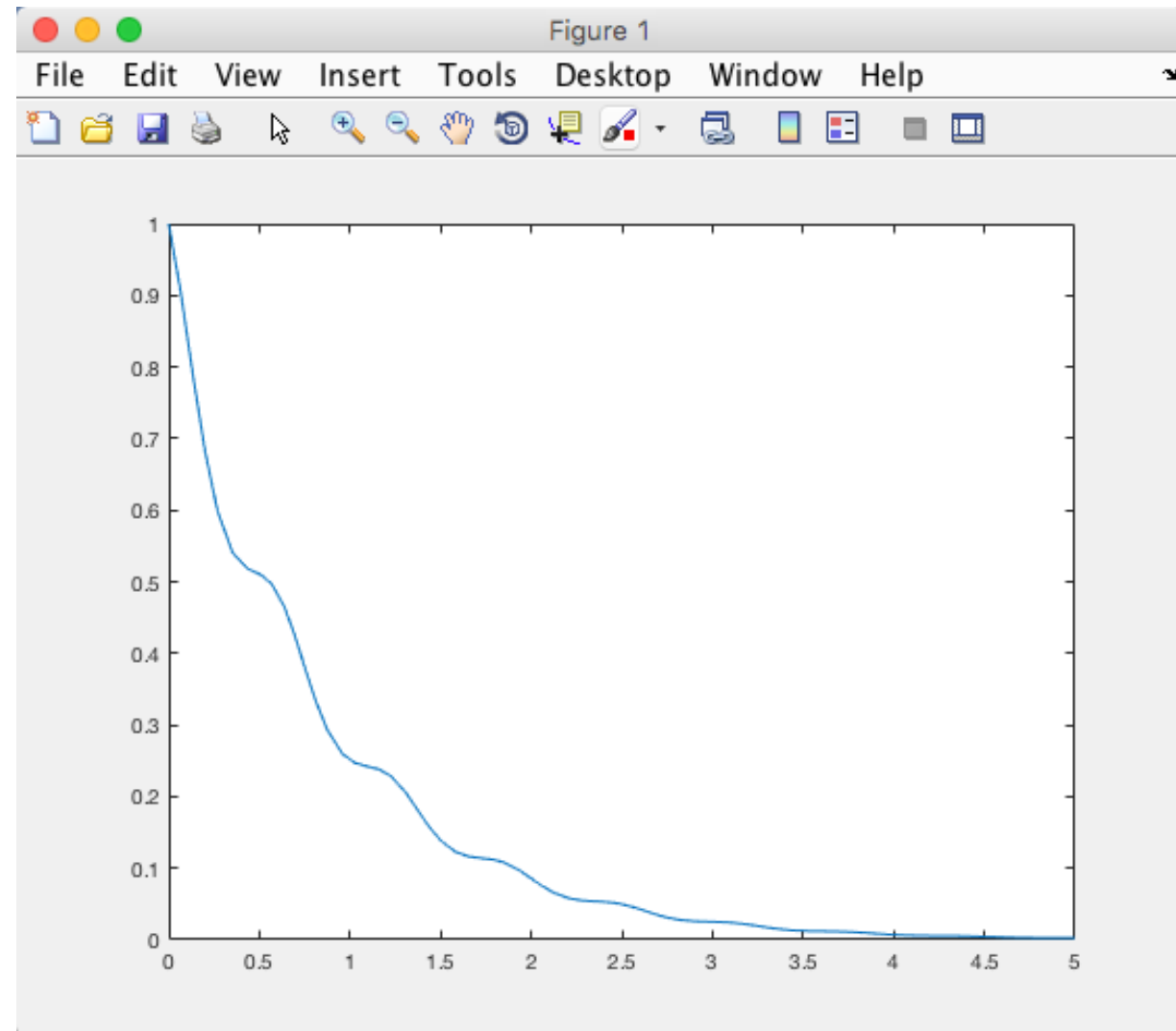
```
dw = -(1.2 + sin(10*t))*w;
```

```
tspan=[0 5];
```

```
w0=1;
```

```
[t,w]=ode23(@diff_task3, tspan, w0);
```

```
plot(t,w)
```



## 2.order differential equation

Use the ode23/ode45 function to solve and plot the results of the following differential equation in the interval  $[t_0, t_f]$ :

$$(1 + t^2)\ddot{w} + 2t\dot{w} + 3w = 2$$

Where; ,  $t_0 = 0, t_f = 5, w(t_0) = 0, \dot{w}(t_0) = 1$

**Note!** Higher order differential equations must be reformulated into a system of first order differential equations.

**Tip 1:** Reformulate the differential equation so  $\ddot{w}$  is alone on the left side.

**Tip 2:** Set:

$$w = x_1$$

$$\dot{w} = x_2$$

## 2.order differential equation

Tip1: First we rewrite like this:

$$\ddot{w} = \frac{2 - 2t\dot{w} - 3w}{(1 + t^2)}$$

Tip2: In order to solve it using the ode functions in MATLAB it has to be a set with 1.order ode's. So we set:

$$w = x_1$$

$$\dot{w} = x_2$$

This gives 2 first order differential equations:

$$\begin{aligned} \dot{x}_1 &= x_2 \\ \dot{x}_2 &= \frac{2 - 2tx_2 - 3x_1}{(1 + t^2)} \end{aligned}$$

```
function dx = diff_secondorder(t,x)
```

```
[m,n] = size(x);
```

```
dx = zeros(m,n)
```

```
dx(1) = x(2);
```

```
dx(2) = (2-2*t*x(2)-3*x(1))/(1+t^2);
```

```
tspan=[0 5];
```

```
x0=[0; 1];
```

```
[t,x]=ode23(@diff_secondorder, tspan, x0);
```

```
plot(t,x)
```

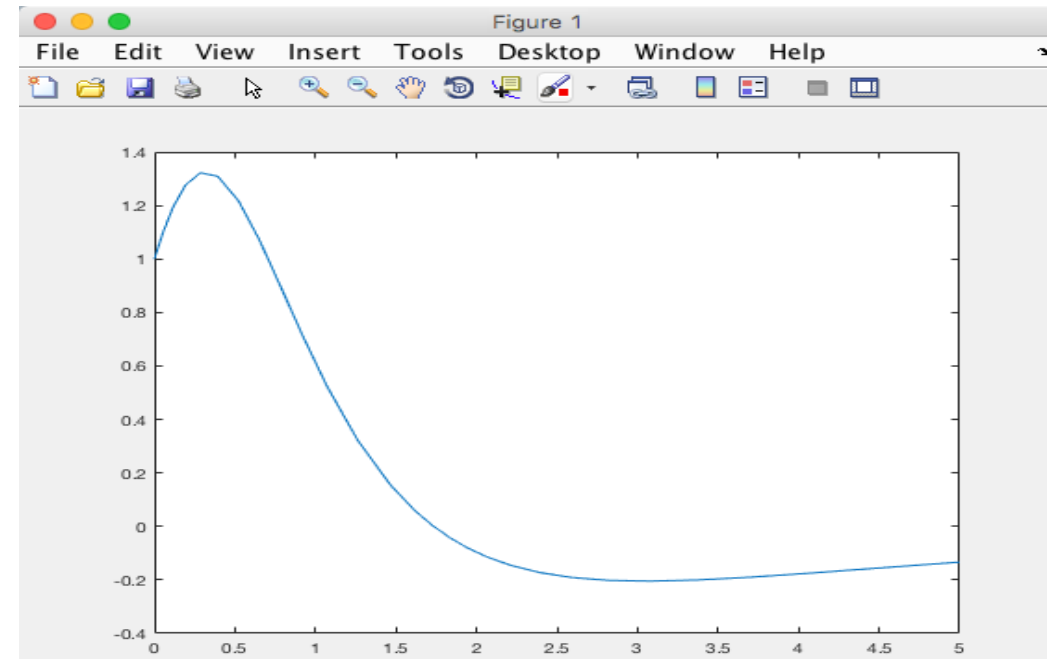
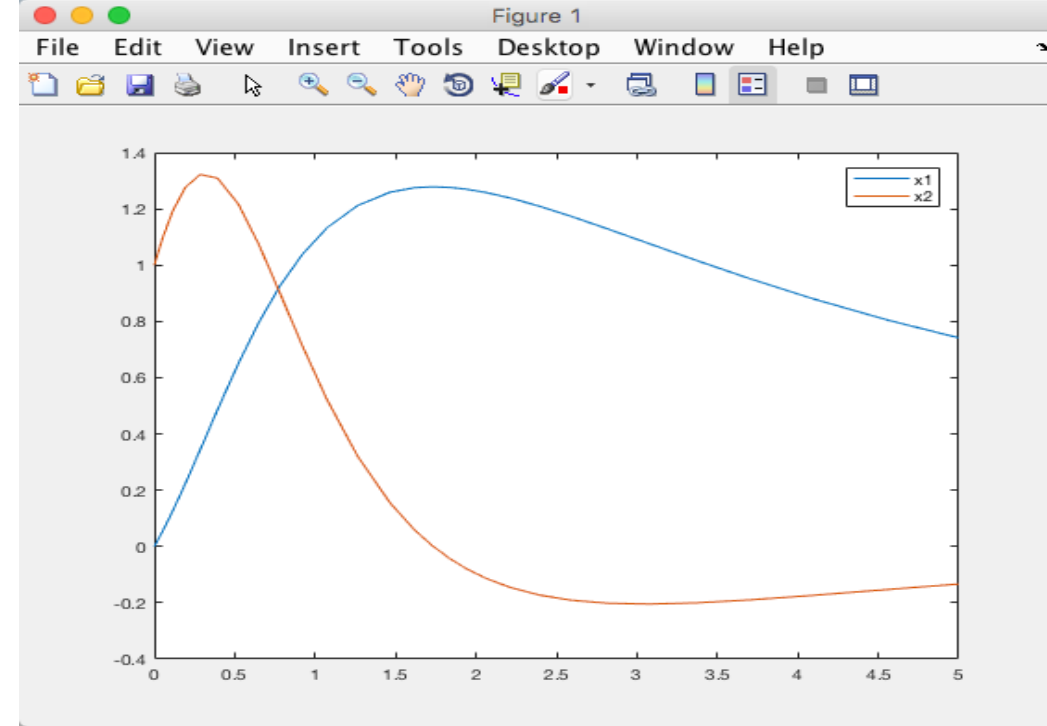
```
legend('x1','x2')
```

```
tspan=[0 5];
```

```
x0=[0; 1];
```

```
[t,x]=ode23(@diff_secondorder, tspan, x0);
```

```
plot(t, x(:,2))
```



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